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Data

Interactively Picking Real-World Objects with Unconstrained Spoken Language Instructions [Hatori+, 2017] https://arxiv.org/abs/1710.06280



Data is king

Can you beat the baseline method using 10x more data?

#citations: ImageNet vs. Dropout

Note: Figures are retrieved from Google scholar

| | TITLE | CITED BY | YEAR |
|----------|---|----------|------|
| ImageNet | Imagenet: A large-scale hierarchical image database J Deng, W Dong, R Socher, LJ Li, K Li, L Fei-Fei Computer Vision and Pattern Recognition, 2009. CVPR 2009. IEEE Conference on … | 5315 | 2009 |
| 9200+ | Imagenet large scale visual recognition challenge O Russakovsky, J Deng, H Su, J Krause, S Satheesh, S Ma, Z Huang, International Journal of Computer Vision 115 (3), 211-252 | 3973 | 2015 |
| | TITLE | CITED BY | YEAR |
| Dropout | Dropout: a simple way to prevent neural networks from overfitting. N Srivastava, GE Hinton, A Krizhevsky, I Sutskever, R Salakhutdinov Journal of machine learning research 15 (1), 1929-1958 | 4272 | 2014 |
| 6500+ | Improving neural networks by preventing co-adaptation of feature detectors GE Hinton, N Srivastava, A Krizhevsky, I Sutskever, RR Salakhutdinov arXiv preprint arXiv:1207.0580 | 2295 | 2012 |

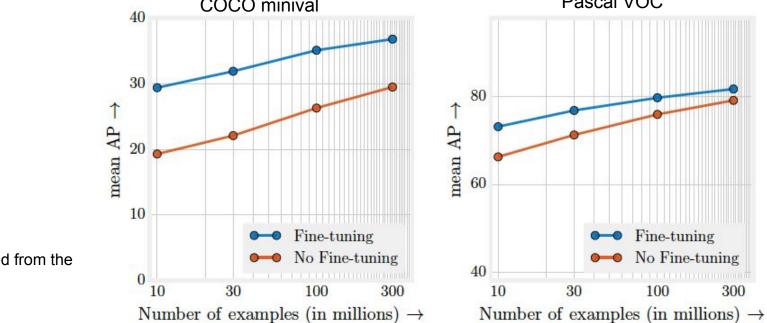
Datasets vs. Algorithms

Figure is retrieved from http://www.spacemachine.net/views/2016/3/datasets-over-algorithms

| Year | Breakthroughs in Al | Datasets (First Available) | Algorithms (First Proposed) | |
|-------|--|--|--|--|
| 1994 | Human-level spontaneous speech recognition | Spoken Wall Street Journal articles and other texts (1991) | Hidden Markov Model (1984) | |
| 1997 | IBM Deep Blue defeated Garry Kasparov | 700,000 Grandmaster chess games, aka "The Extended Book" (1991) | Negascout planning algorithm (1983) | |
| 2005 | Google's Arabic- and Chinese-to-English translation | 1.8 trillion tokens from Google Web and News pages (collected in 2005) | Statistical machine translation algorithm (1988) | |
| 2011 | IBM Watson became the world Jeopardy! champion | 8.6 million documents from Wikipedia, Wiktionary, Wikiquote, and Project Gutenberg (updated in 2010) | Mixture-of-Experts algorithm (1991) | |
| 2014 | Google's GoogLeNet object classification at near-human performance | ImageNet corpus of 1.5 million labeled images and 1,000 object categories (2010) | Convolution neural network algorithm (1989) | |
| 2015 | Google's Deepmind achieved human parity in playing 29 Atari games by learning general control from video | Arcade Learning Environment dataset of over 50 Atari games (2013) | Q-learning algorithm (1992) | |
| Avera | Average No. of Years to Breakthrough: 3 years 18 years | | | |

Performance increases linearly with orders of magnitude of training data!

Revisiting Unreasonable Effectiveness of Data in Deep Learning Era [Sun+,
2017]COCO minivalPascal VOC



Figures are retrieved from the original paper

Supervised Data

 Manual annotations (the first wave)



RefCOCO+



guy in yellow dirbbling ball yellow shirt and black shorts yellow shirt in focus



https://github.com/lichengunc/refer

Logs of human/bussiness activities (the second wave)



The third wave

• Self-play / self-supervised data

AlphaGo Zero [Silver+, 2017] → Self-play data

- Learning from scratch: learns to play simply by playing games against itself
 - AlphaGo was initially trained on thousands of human games

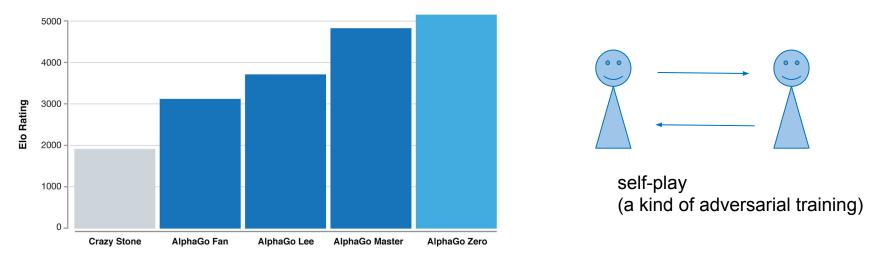
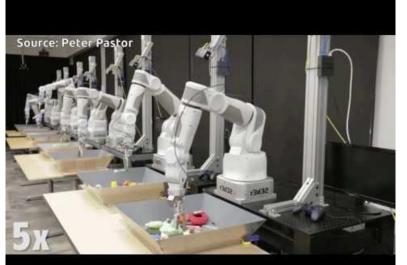


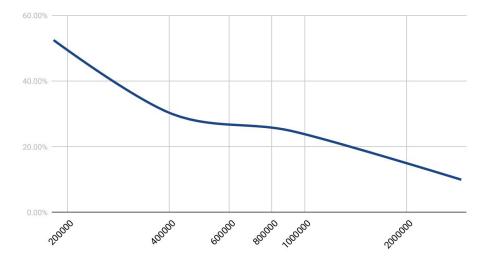
Figure is retrieved from https://deepmind.com/blog/alphago-zero-learning-scratch/

Self-supervised data for visual robot control Two months using 6 - 14 robotic manipulators

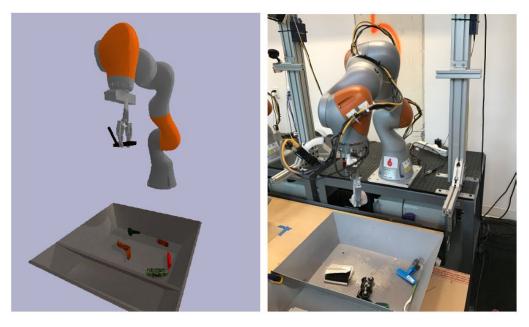
Learning Hand-Eye Coordination for Robotic Grasping with Deep Learning and Large-Scale Data Collection [Levin+, 2016]



Failure rates of grasp for varying dataset sizes



Self-supervised data generated by simulator



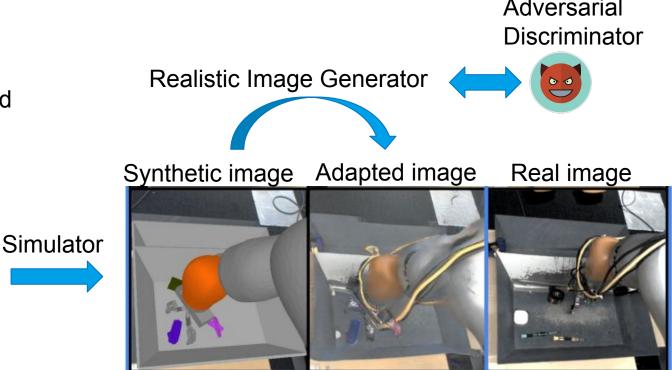
Physical experiments are extremely time-consuming and expensive \rightarrow Using simulator to generate synthetic experience (2K simulated robots)

Using Simulation and Domain Adaptation to Improve Efficiency of Deep Robotic Grasping [Bousmalis+, 2017]

Bridging the reality gap by domain adaptation techniques [Bousmalis+, 2017] Adversarial

Procedurally generated random objects





Figures are retrieved from the original paper

Take-home messages

- Data might be the key limiting factor to development of AI
- Self-play or self-supervised data could be the third wave
- Simulators could exceed the limit of physical environment

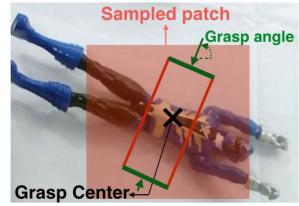


Figure is retrieved from [Pinto and Gupta, 2015]